

All-ion Accelerators

- New Trend of Induction Synchrotron -

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Contents

Experimental results of induction acceleration in the KEK 12GeV PS

Idea of all-ion accelerators

Its applications

Summary

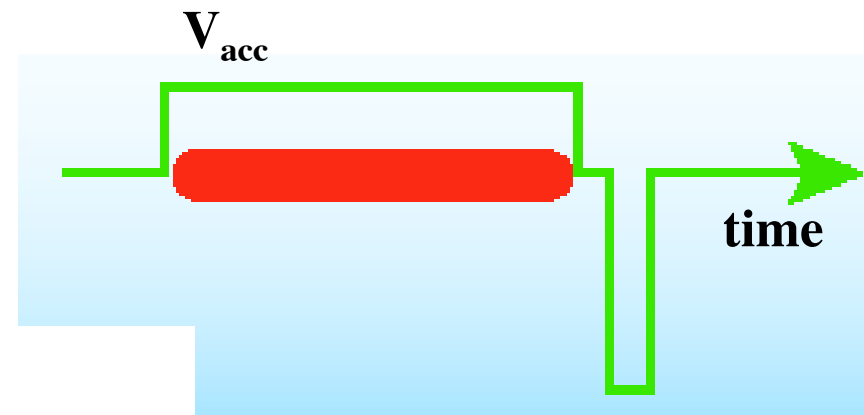
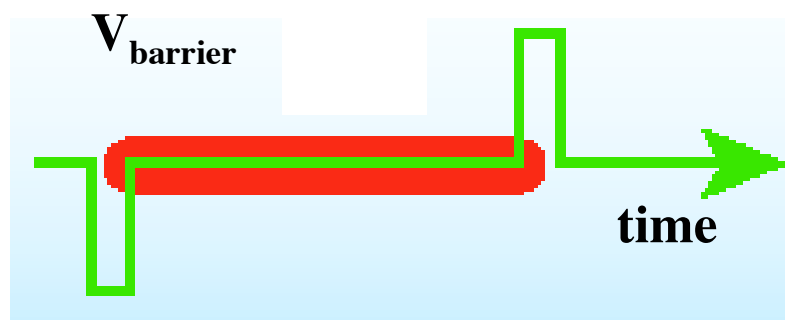
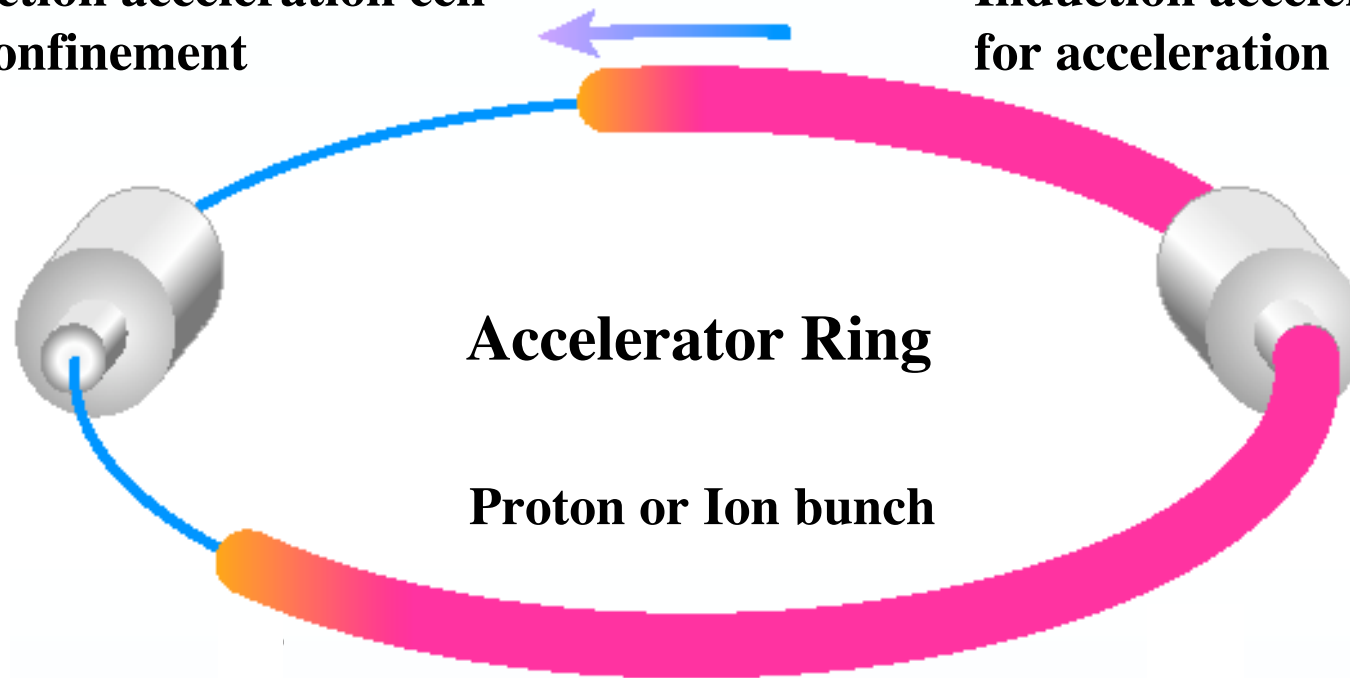
US-Japan Inertial Fusion Workshop 28/9/2005 at Utsunomiya University

Schematic View of Induction Synchrotron

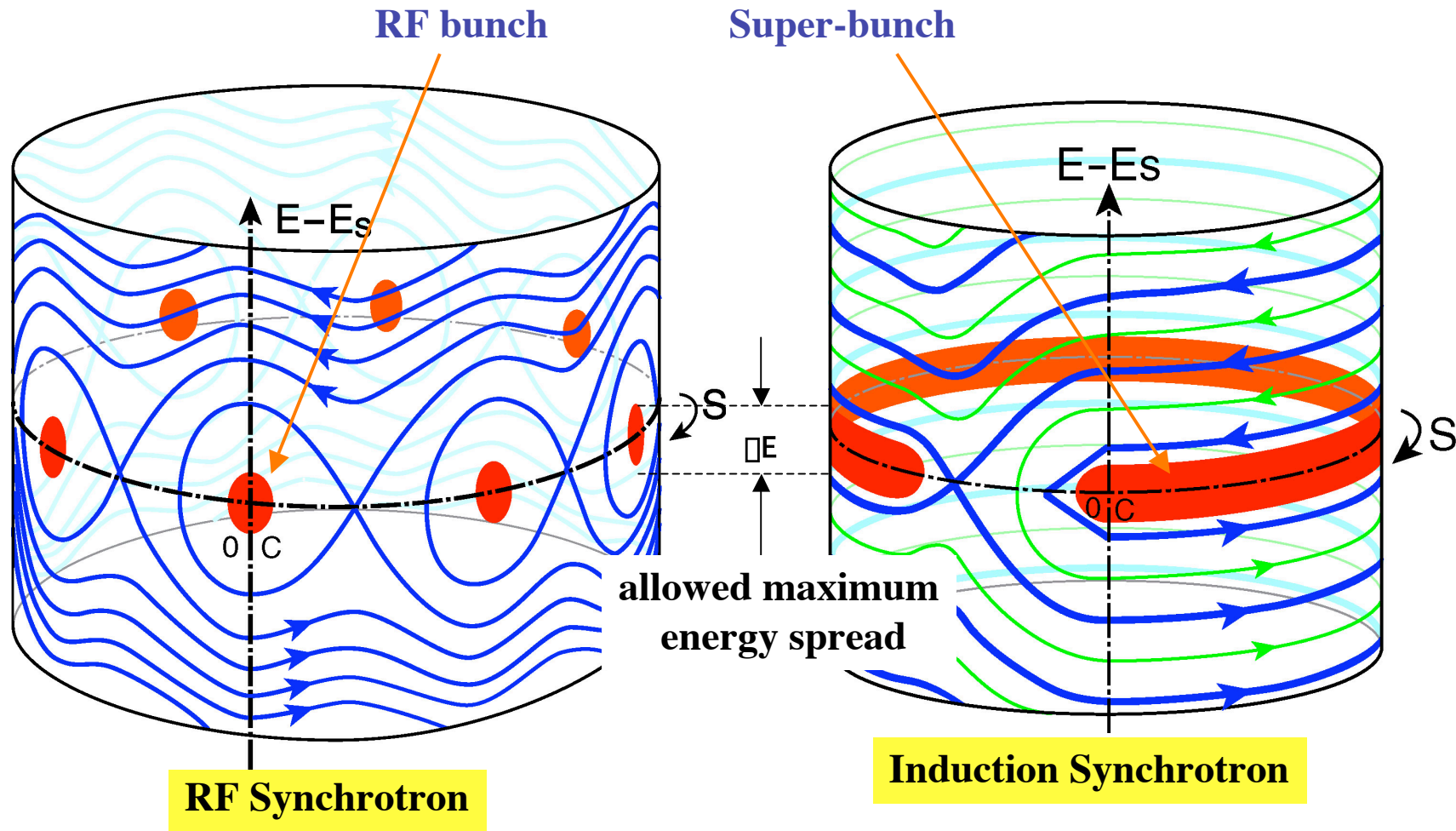
Separated function in the longitudinal direction

Induction acceleration cell
for confinement

Induction acceleration cell
for acceleration

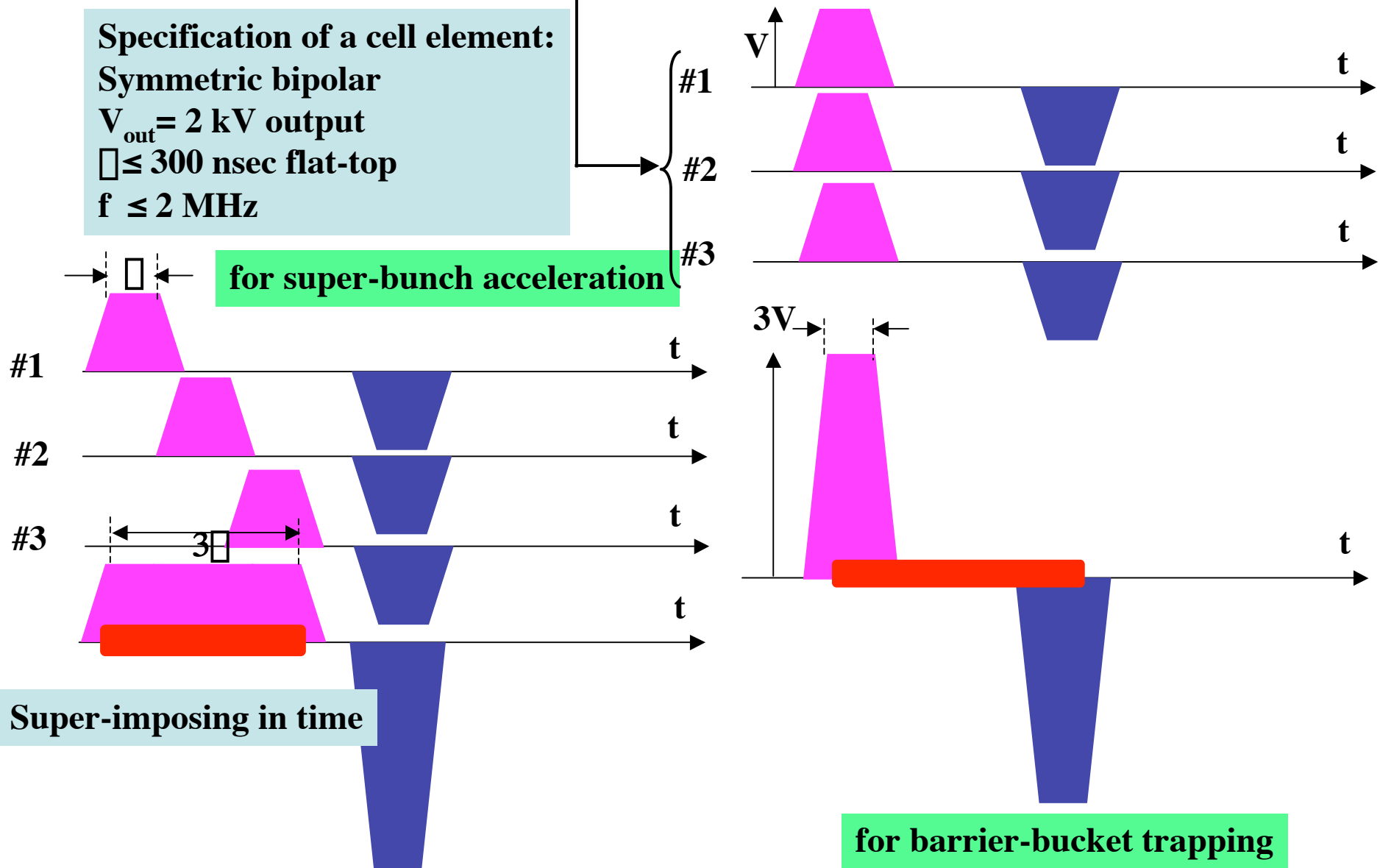


Difference between RF Synchrotron and Induction Synchrotron seen in Phase-space

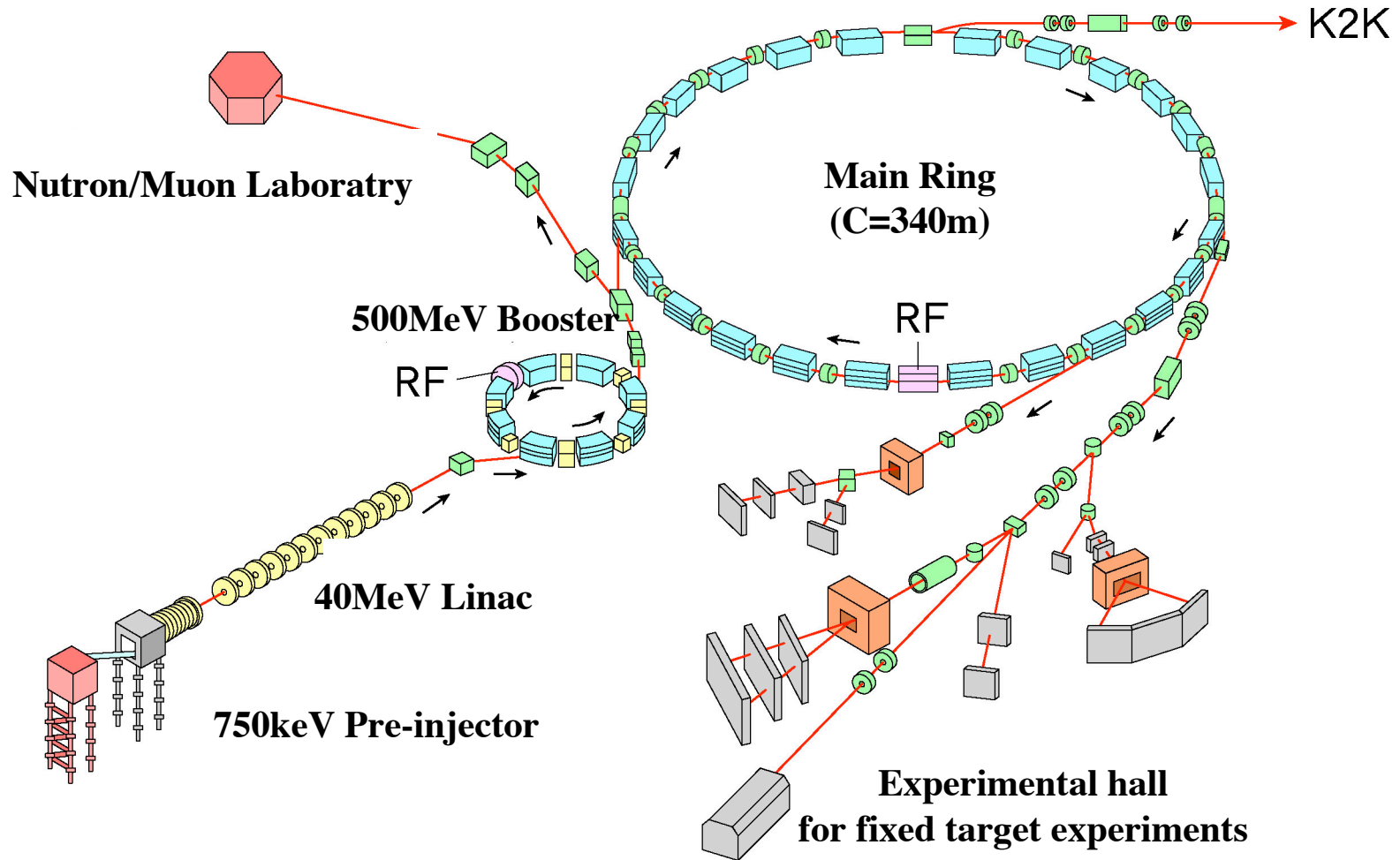


**Possible scheme to generate induction step-voltage
for a barrier bucket and super-bunch acceleration
assuming the basic flip-flop operation of an single unit**

Specification of a cell element:
Symmetric bipolar
 $V_{out} = 2 \text{ kV}$ output
 $\tau \leq 300 \text{ nsec}$ flat-top
 $f \leq 2 \text{ MHz}$



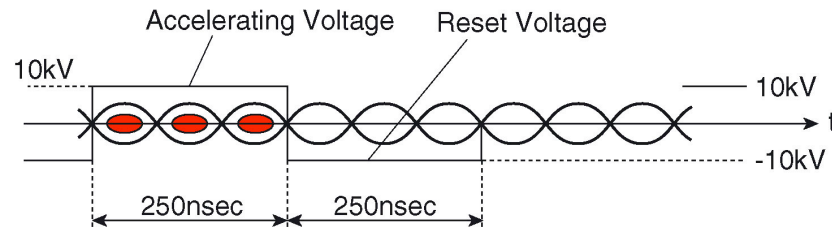
KEK 12GeV PS



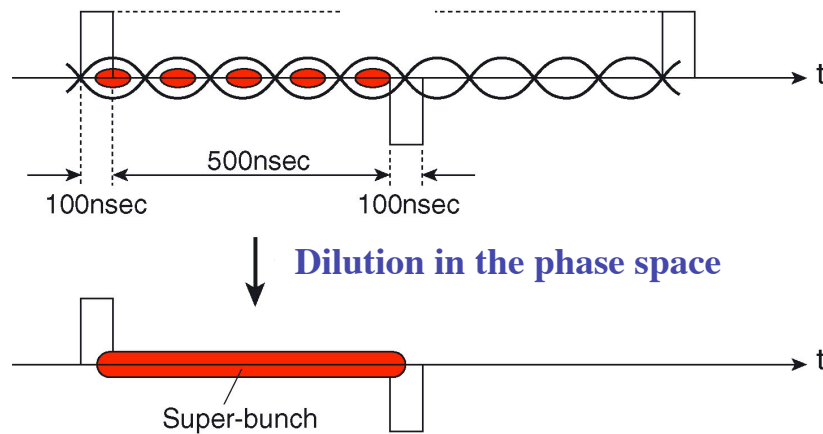
Scenario of POP Experiment

Induction acceleration system: output voltage 2kV/set

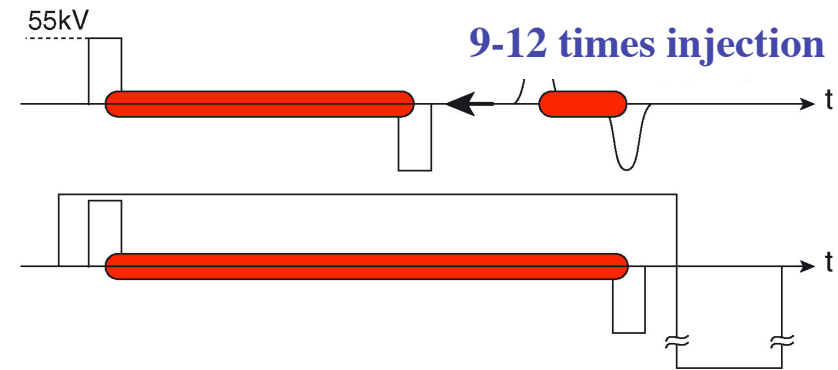
Step 1 Acceleration: Induction (500MeV->8GeV)
Confinement: RF with 3 sets



Step 2 Super-bunch formation at 500MeV with 3/6 sets



Step 3 Super-bunch Stacking
Acceleration (500MeV -> 8GeV)



Final goal is to modify the KEK PS (RF synchrotron) to an Induction Synchrotron at the last stage of its 30 years life.

KEK PS Accelerator Complex & Induction Accelerating System

Switching Power Supplies

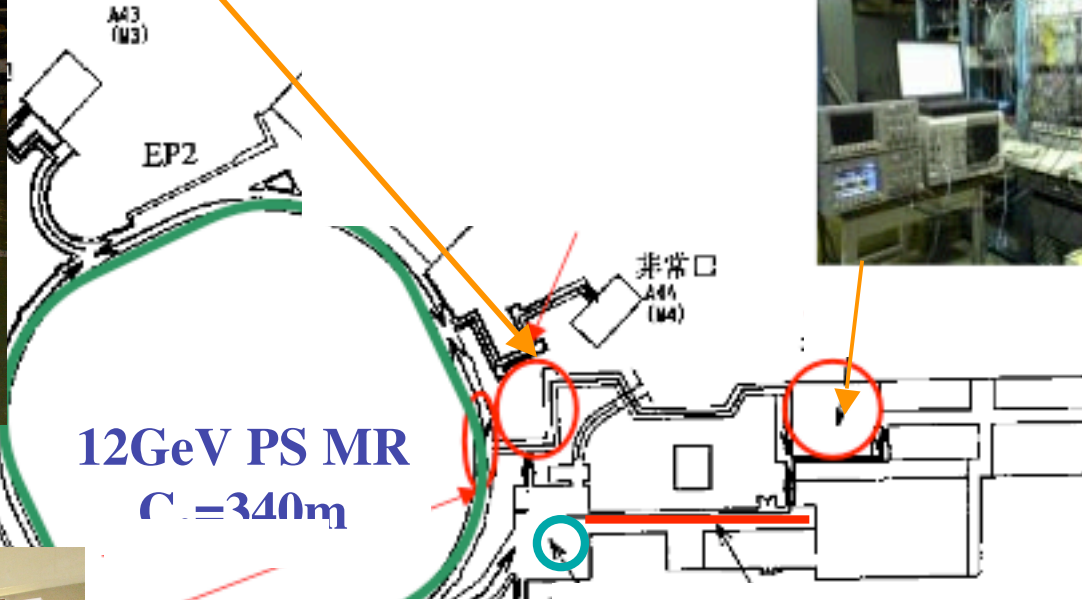
Main Trigger Generator at CCR



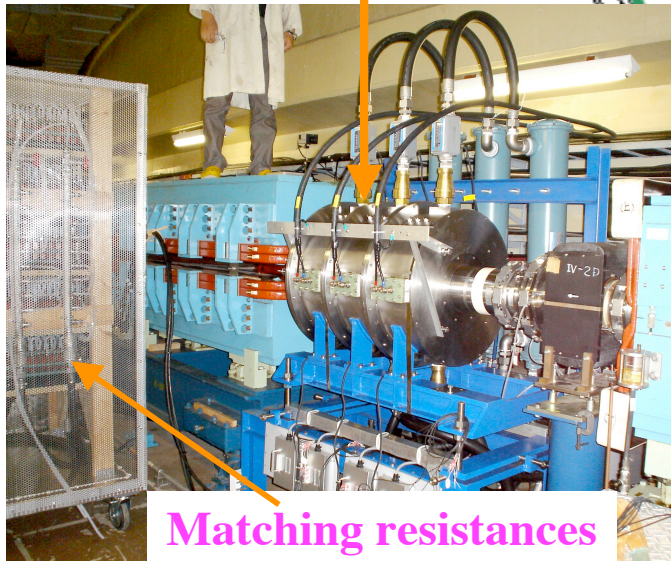
Induction Cells (3 cells)

EP1

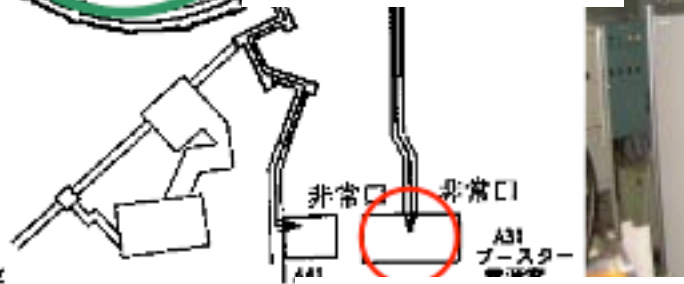
12GeV PS MR
 $C = 340m$



500MeV Booster 40MeV Linac



Matching resistances



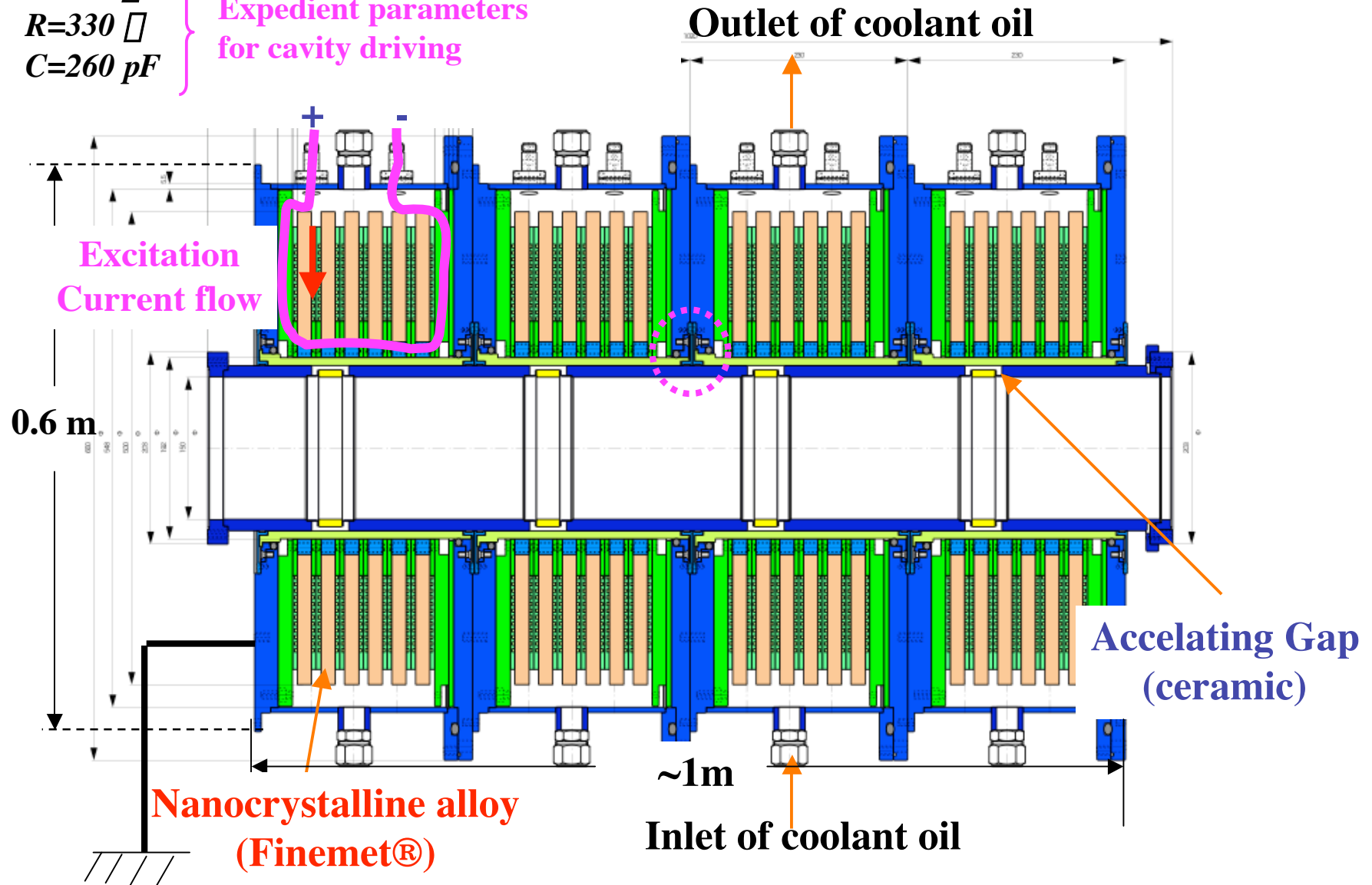
DC power Supply



Induction Acceleration Cavity consisted of 4 Cells(2kV/cell) and a single inner chamber

$L=110 \text{ nH}$
 $R=330 \text{ }\Omega$
 $C=260 \text{ pF}$

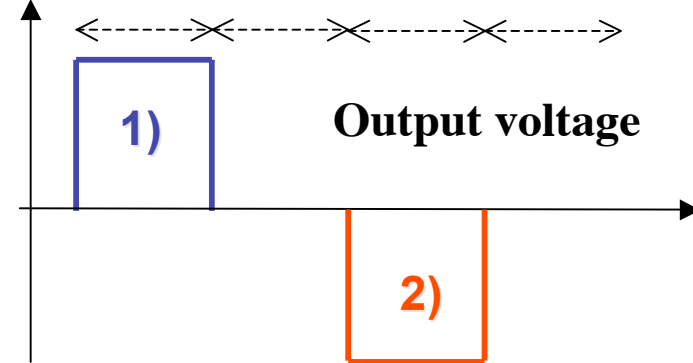
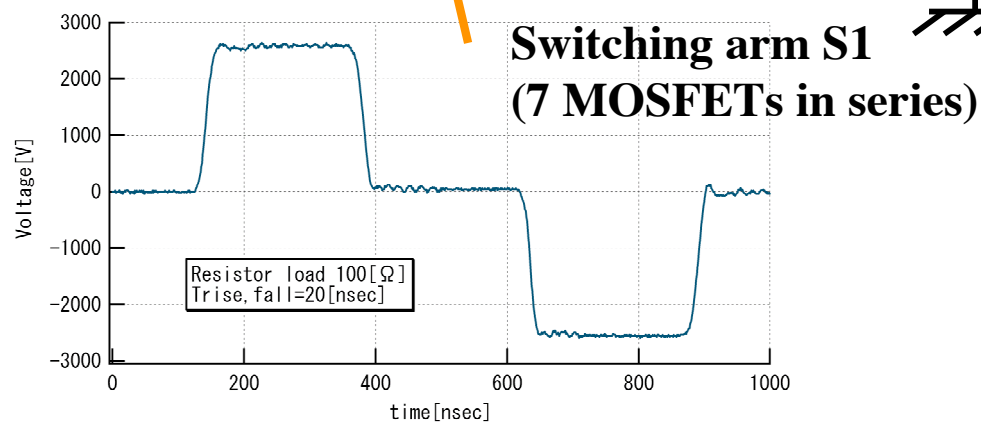
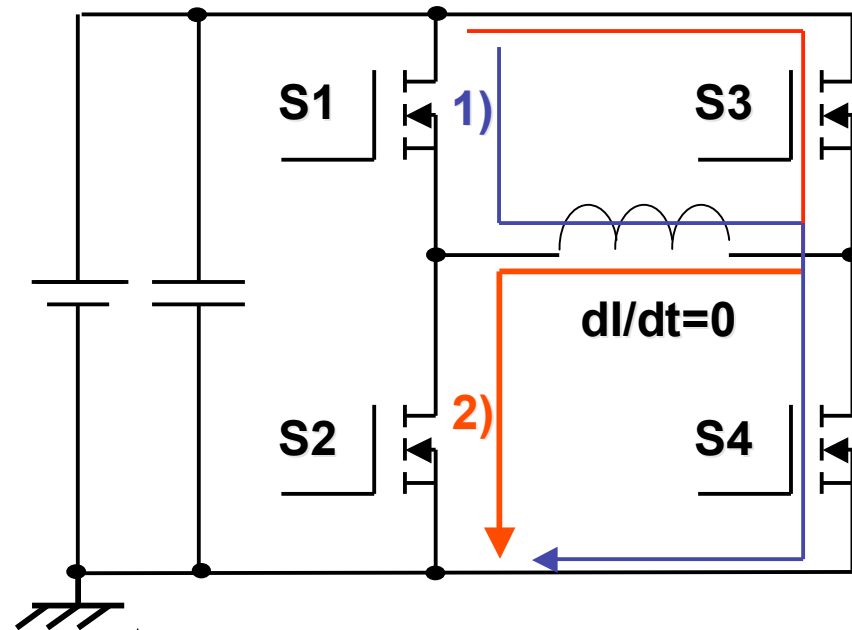
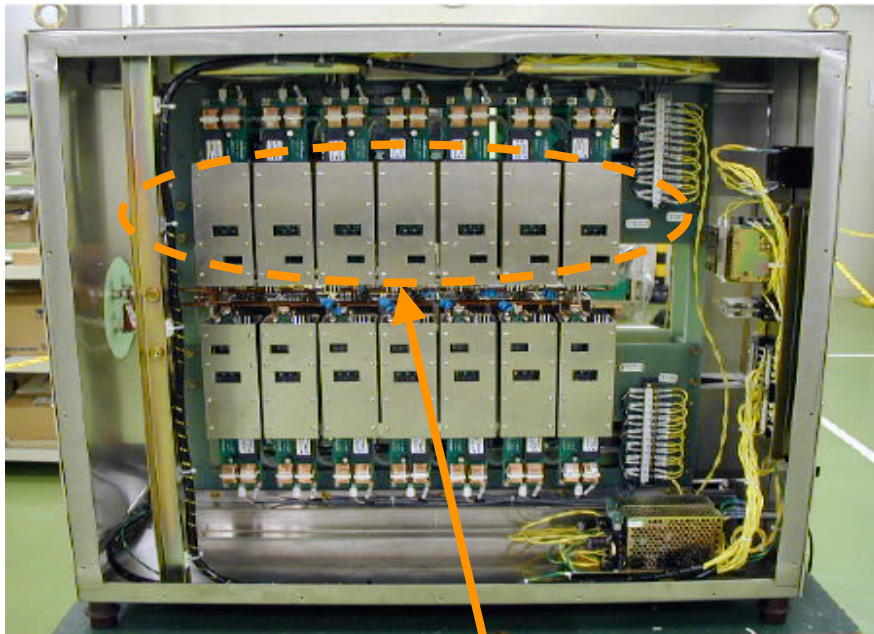
Expedient parameters
for cavity driving



Switching Power Supply: switching sequence, output pulse

2.5kV, 20A, 1MHz, 500nsec

designed and measured by Koseki *et al.* (KEK)
assembled at Nichicon

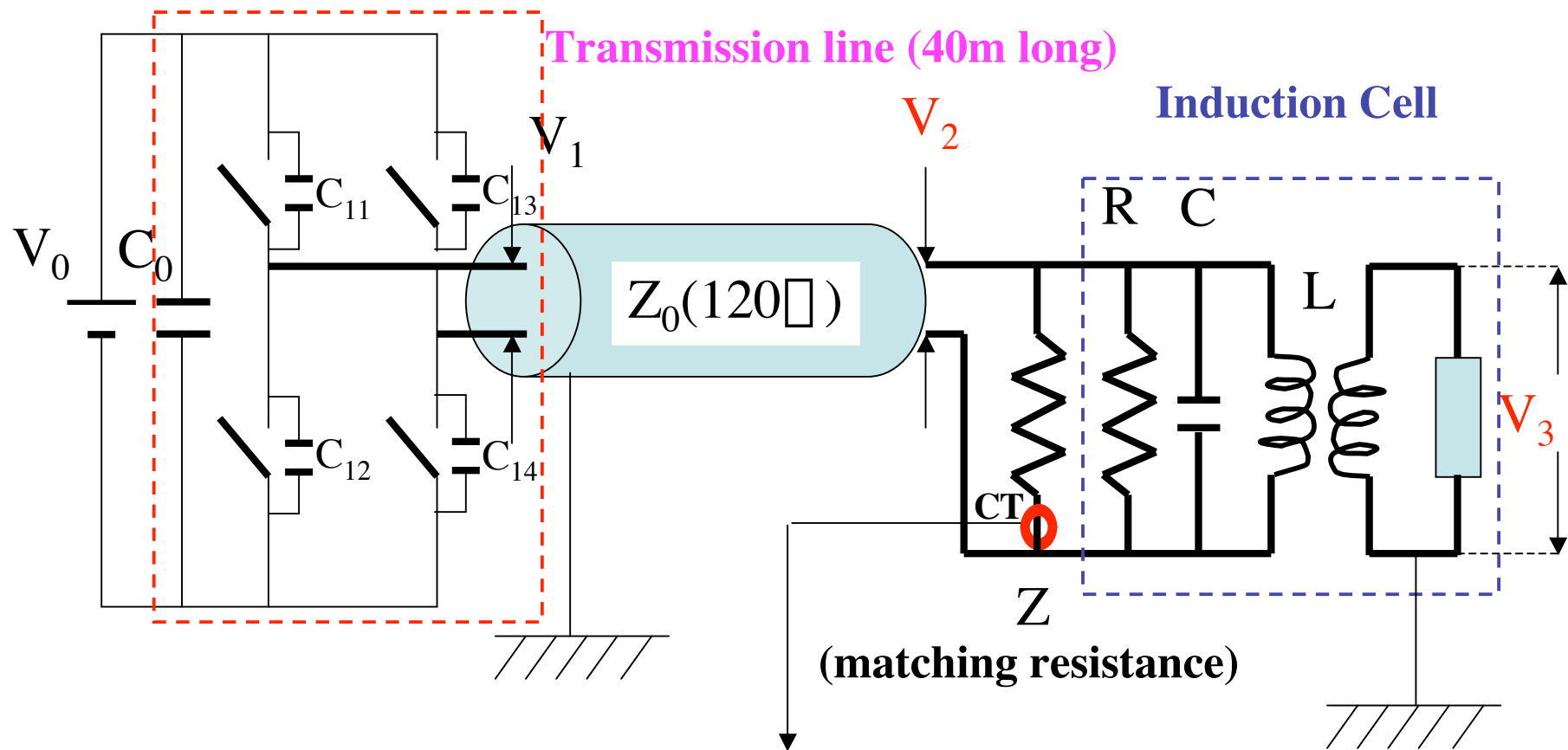


Key point: pulse voltage can be generated at timing and with pulse duration that you want, by controlling a gate pulse of the MOSFETs.

Equivalent Circuit for Induction Accelerating System

DC P.S.

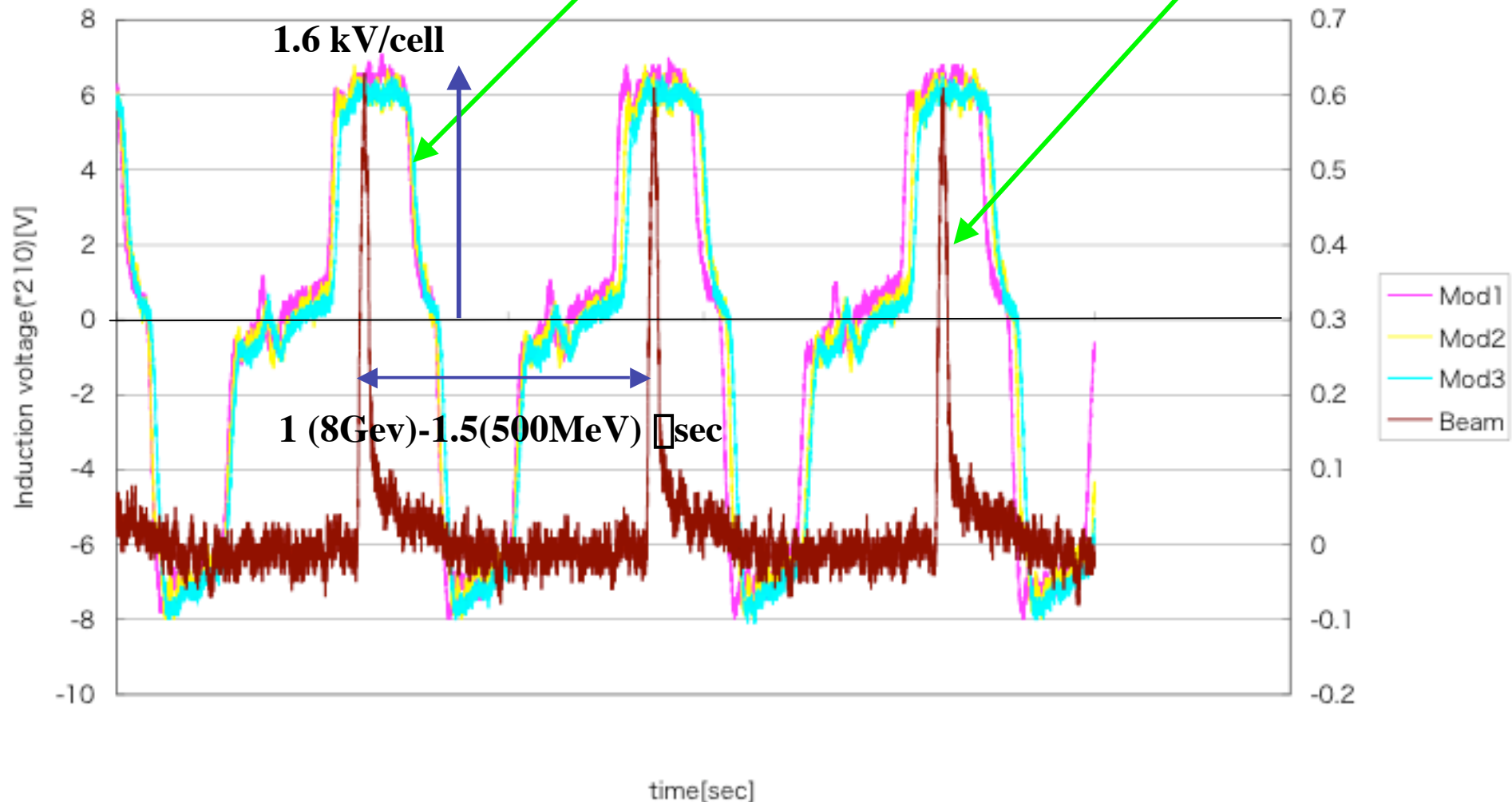
Switching P.S.



$V_0 \sim V_2 = V_3 \sim Z I_Z$ (calibrated)

I_Z (always monitored at CCR)

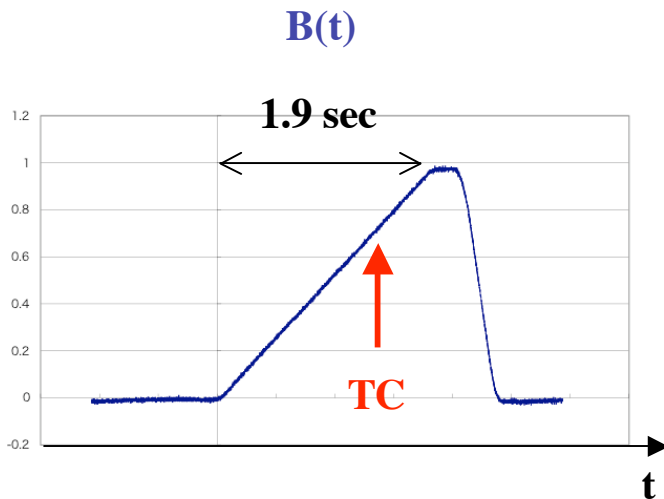
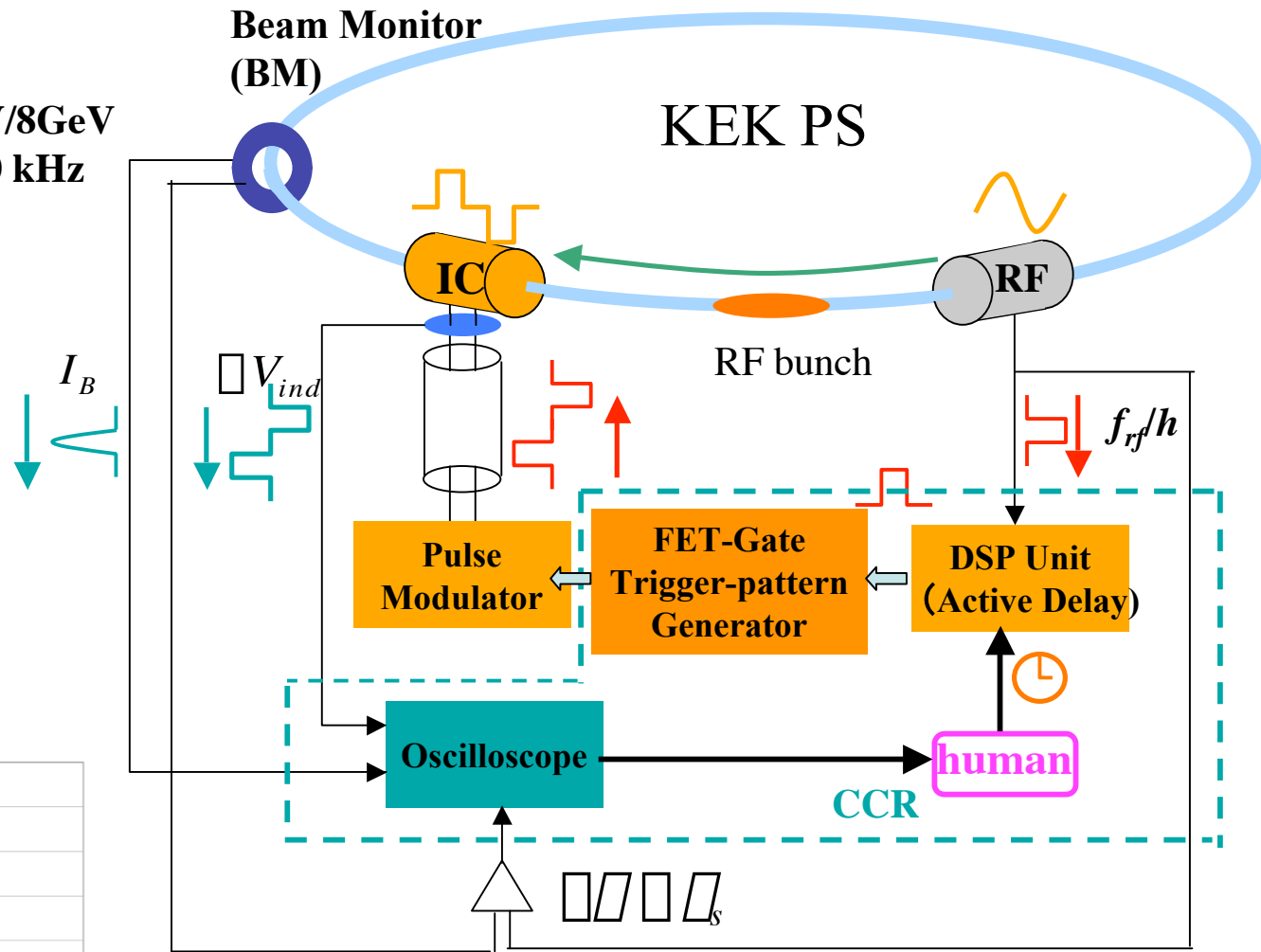
Monitored signals of induction voltage and an RF bunch signal



- Beam bunch signal was monitored at the 4th acceleration gap.
- Synchronization between two signals has been confirmed through an entire acceleration.

Machine Parameters and Control/Monitoring System

Circumference	339m
Trans. energy \square	6.68
Inj./ext. energy	500MeV/8GeV
Rev. frequency	667-880 kHz
Ramping time	1.9sec
RF voltage	48 kV
Harmonic numb.	9
Induction voltage	4.8 kV



Theoretical background to confirm induction acceleration

Force balance in the radial direction:

$$m\gamma \cdot \frac{(c\beta)^2}{\rho} = e c \beta \cdot B(t)$$

Acceleration equation:

$$m c^2 \cdot \dot{\beta} = \frac{e c \beta}{C_0} \cdot V_{acc}(t)$$

given by ramping pattern of bending field



$$V_{acc}(t) = \beta \cdot C_0 \cdot dB/dt$$

Desired acceleration condition

Voltage received by bunch center:

$$V(t) = V_{rf} \sin \varphi_s + V_{ind}$$

$$V(t) = V_{acc}(t)$$

$$\downarrow V_{acc}(t) = V_0 (\text{constant for linear ramp: } dB/dt = \text{constant})$$

a) $V_{ind} = V_0$ (acceleration)

b) $V_{ind} = 0$

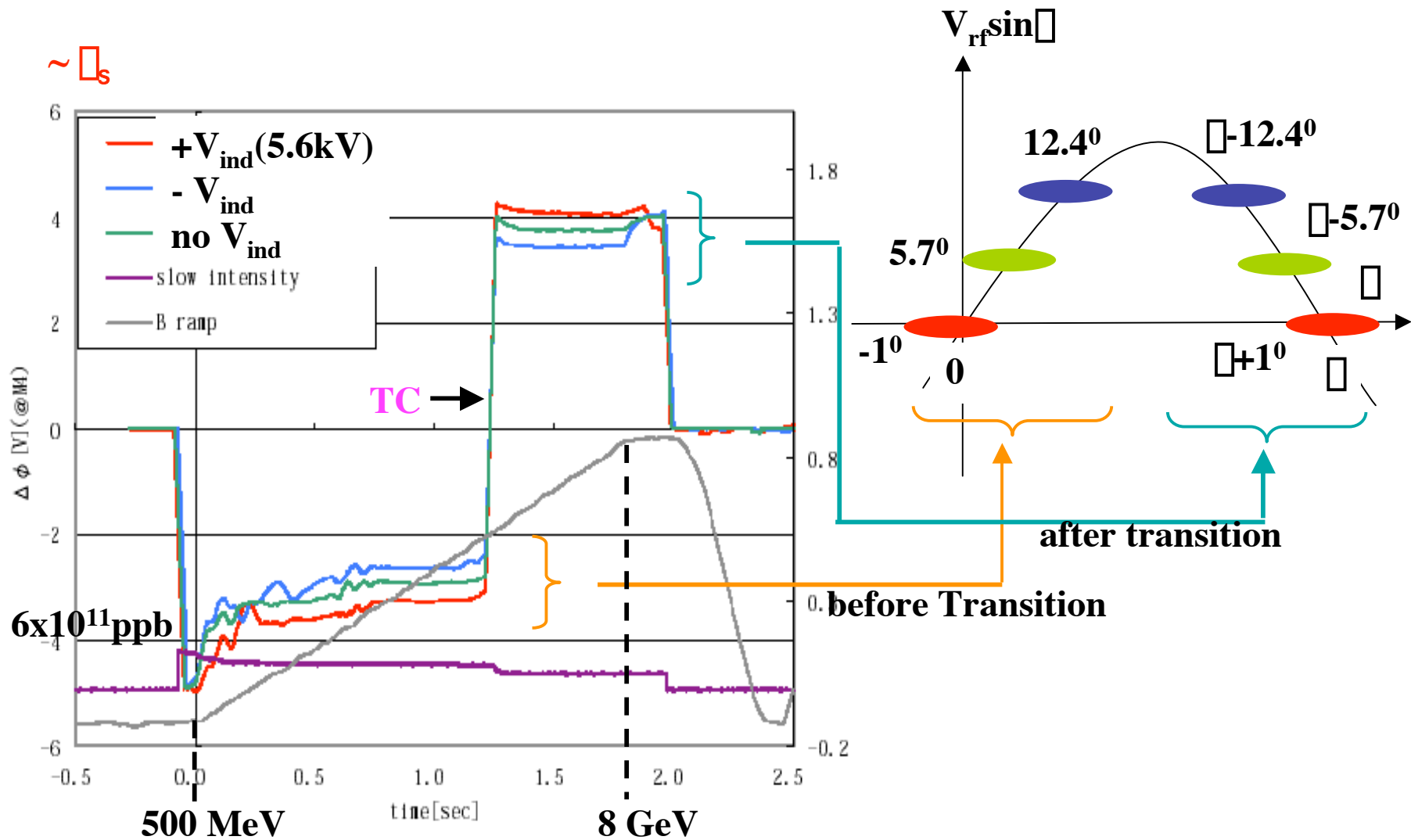
c) $V_{ind} = -V_0$ (deceleration)

$$\varphi_s = \sin^{-1} \left[\frac{V_0}{V_{rf}} \right]$$

$$\varphi_s = \sin^{-1} \left[\frac{2V_0}{V_{rf}} \right]$$

observable as a relative position of an RF bunch to RF phase

Experimental Facts: Change in β_s , Beam Intensity, and B



K.Takayama *et al.*, *Phys. Rev. Lett.* 94, 144801 (2005).

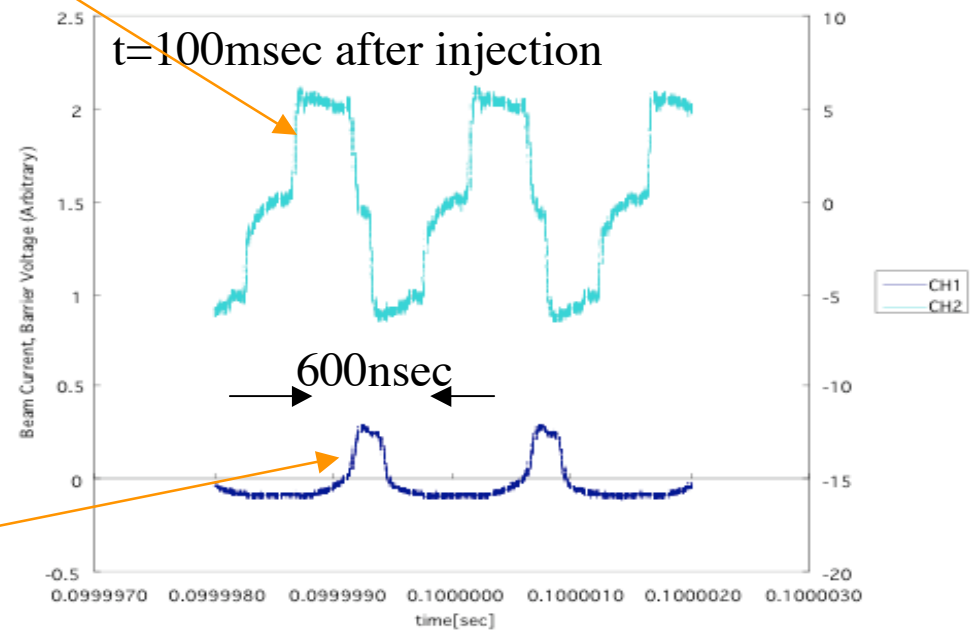
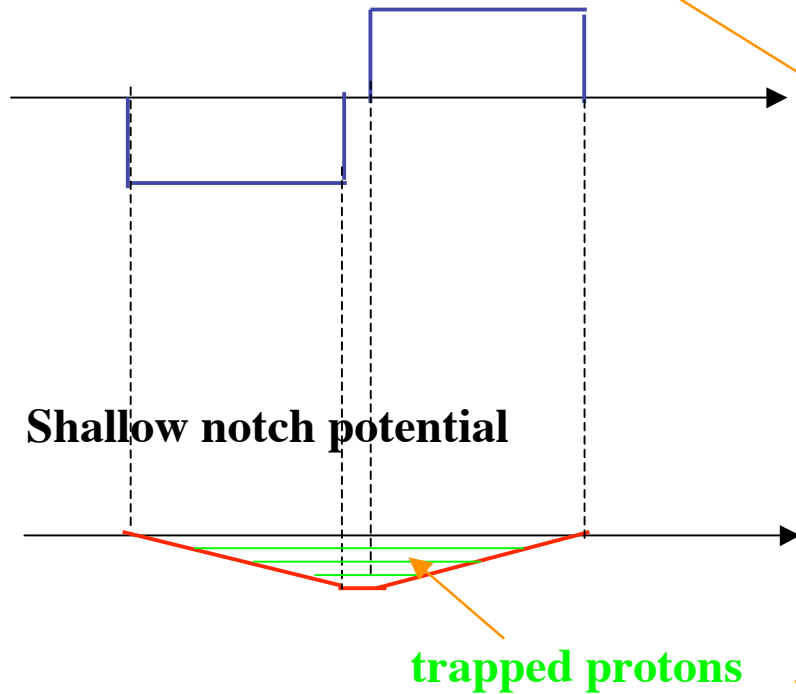


Confinement by Induction Step-barriers

Formation of a 600nsec-long bunch

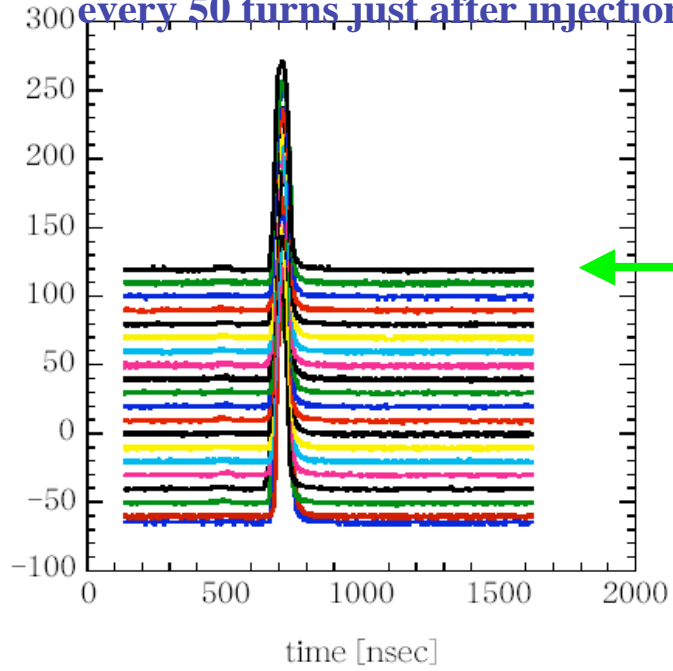
6kV barrier-voltage

injected
proton bunch



RF On

every 50 turns just after injection

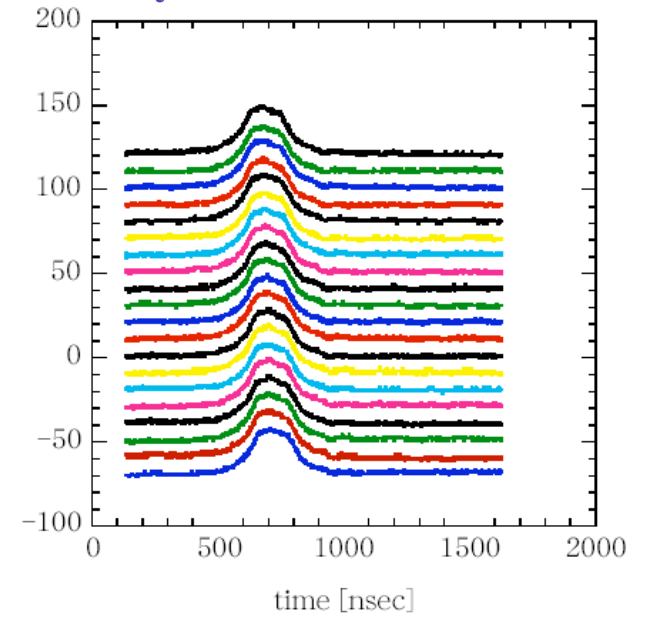


Mountain View

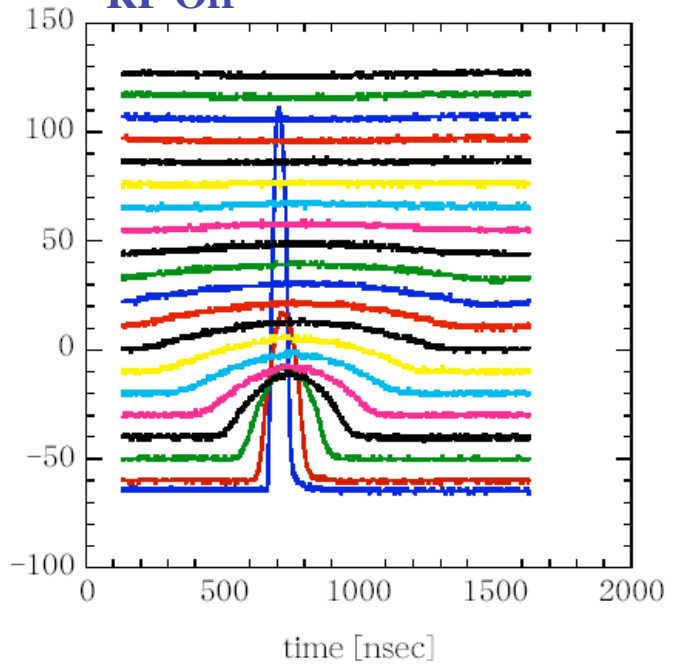
RF bucket Trapping

150msec after injection

every 1 turn



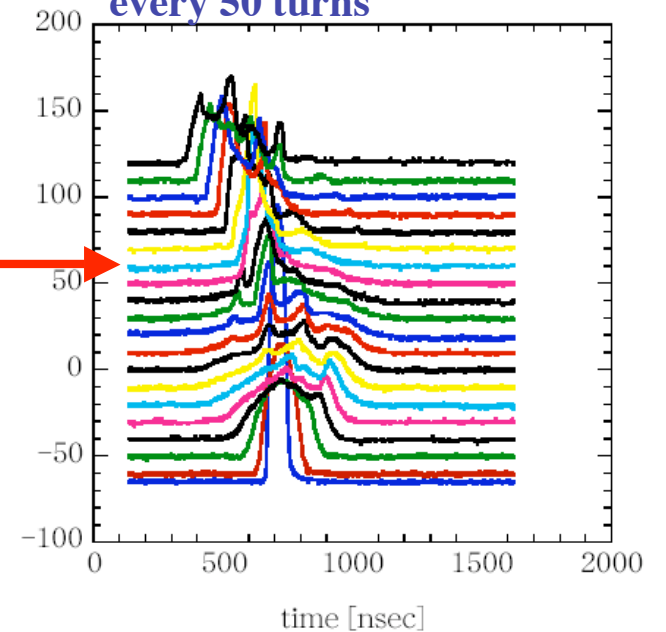
RF Off



Notch Potential Trapping

just after injection

every 50 turns



Schedule of this and next year

task	'04	'05	'06	'08	'09
Induction acceleration of 1 RF bunch from 500MeV to 8GeV with 3 induction acceleration cells	↔				
Confinement with induction step-barrier voltages at 500MeV with 3 cells		↔			
Induction acceleration of 1 barrier trapped bunch to 6 or 8GeV with 6 cells (2 for accel. and 4 for confinement)			↔		
Induction acceleration of a barrier trapped super-bunch to 8GeV with 10 cells (4 for accel. and 6 for confinement)				↔	



We are here now.

Possible Applications of Induction Synchrotron Concept

energy region	Application	Property	
		separated function	arbitrary switching frequency
high energy $E > \text{TeV}$	Super-bunch Hadron Collider K.Takayama et al., <i>PRL</i> 88, 1448(2002), Snowmass 2001	super-bunch	MHz
medium energy $10 \text{ GeV} < E < 1 \text{ TeV}$	Proton Driver K.Takayama and J.Kishiro <i>N.I.M.</i> A451, 304 (2000)	super-bunch	MHz
low energy $1\text{MeV} < E < 10\text{GeV}$	All-ion Accelerator from p to U	bunch combining	kHz -> MHz operation

Motivation for All-ion Accelerators (AIA)

from the experimental demonstration of induction acceleration in the KEK-PS

- Stable performance of the switching power supply from ~ 0 Hz to 1MHz
- Master trigger signal for the switching P.S. can be generated from a circulating beam signal

Allow to accelerate even quite slow particles

Betatron motion doesn't depend on ion mass and charge state, once the magnetic guide fields are fixed.

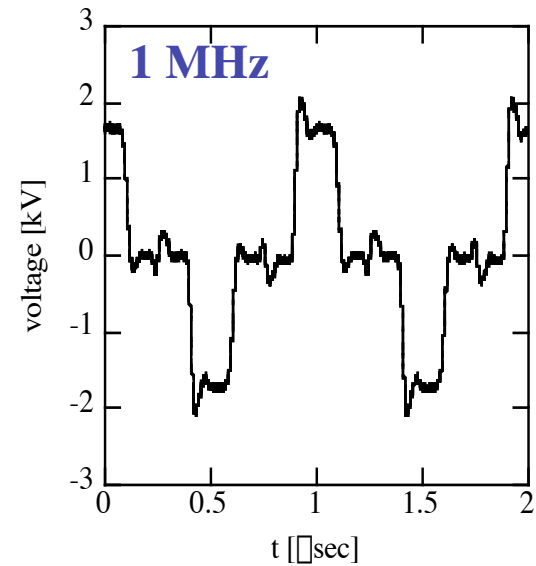
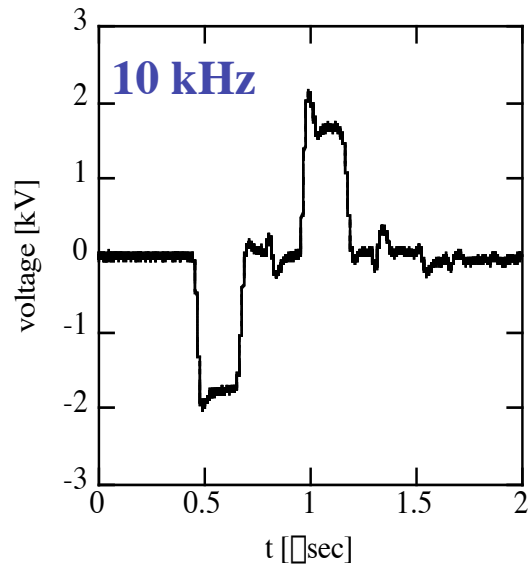
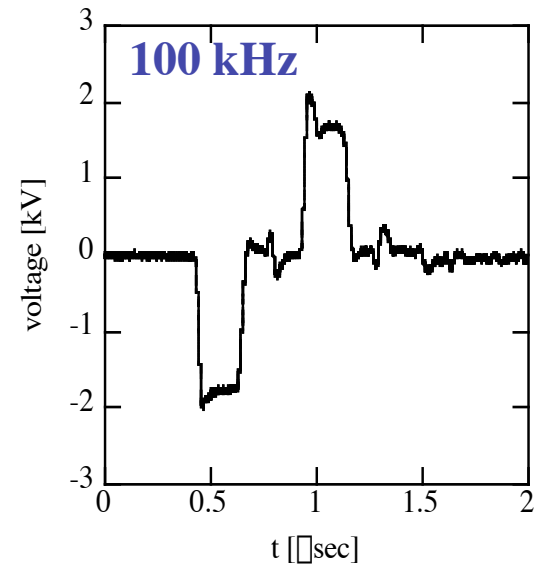
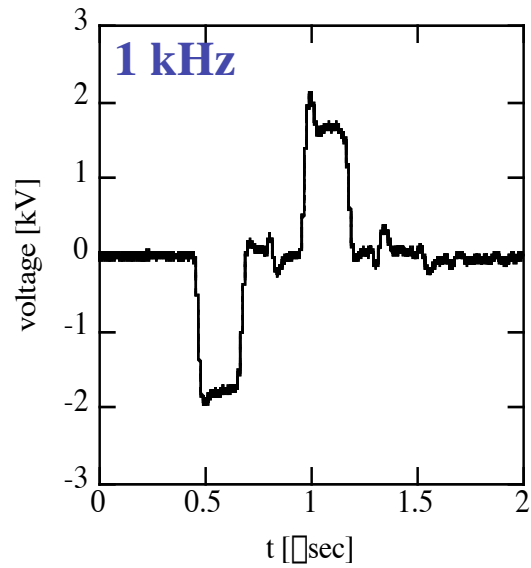
A single circular strong-focusing machine can accelerate from proton to uranium.

Concept of an all-ion accelerator

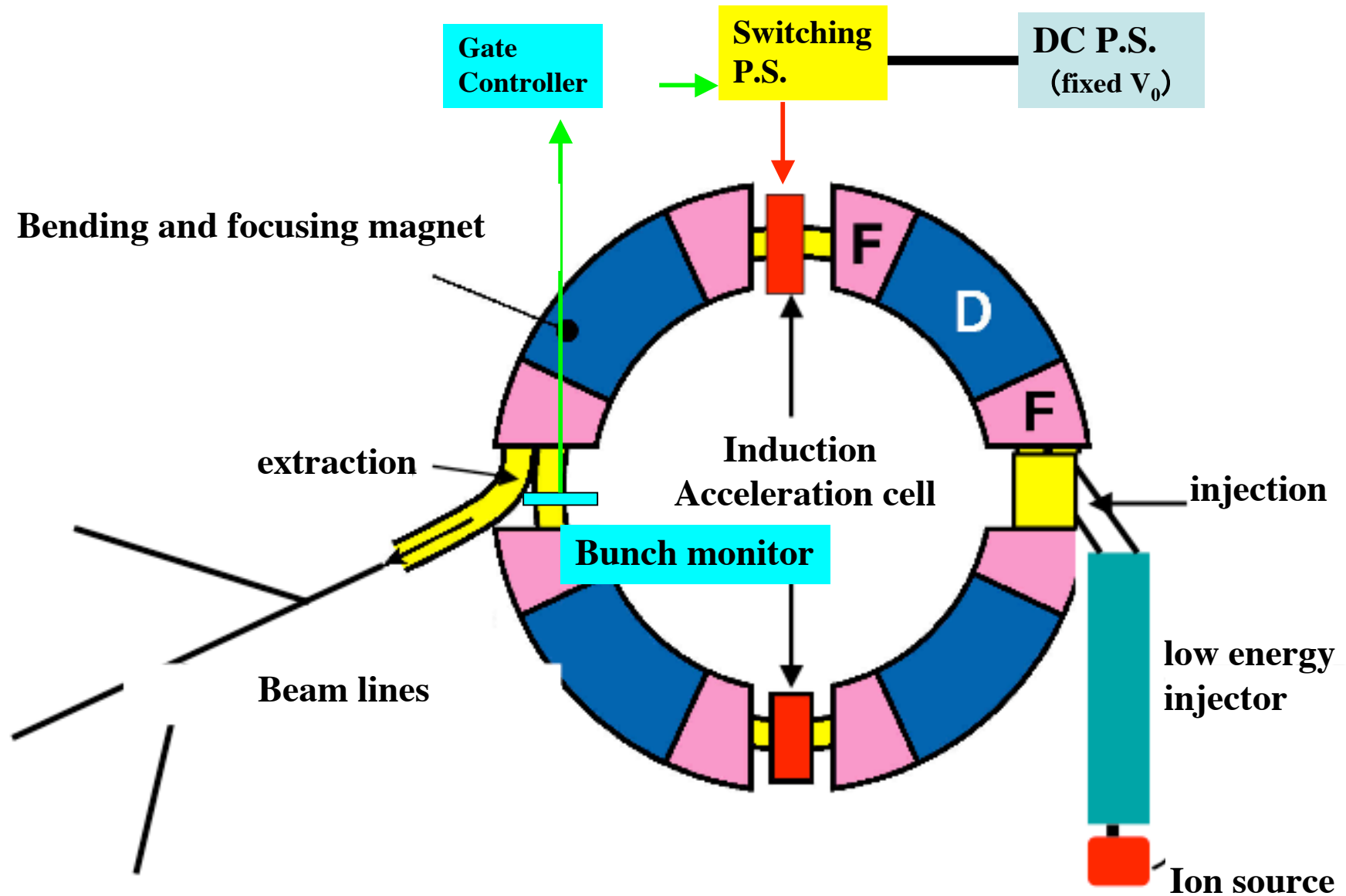
almost injector-free for a low intensity

K.Takayama, K.Torikai, Y.Shimosaki, and Y.Arakida, "**All Ion Accelerators**", submitted for publication (2005) and applying for a patent

Repetition dependence of the induced voltage



Schematic View of AIA



Acceleration in the AIA (1)

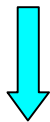
Ion: $M=Am$, $Q=Ze$ (A : mass number, Z : charge state)

Force balance:

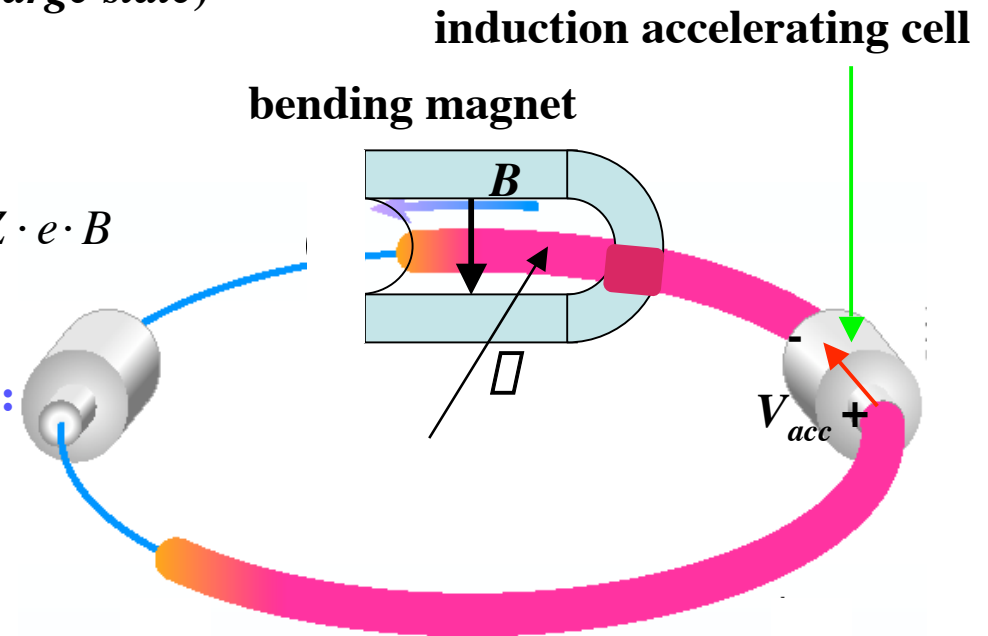
$$M \frac{d^2 r}{dt^2} = Q \cdot (c r) \cdot B \quad \square \quad A \cdot m \cdot \frac{c r}{dt} = Z \cdot e \cdot B$$

Local acceleration \rightarrow averaged acceleration:

$$A \cdot mc^2 \cdot \frac{d\gamma}{dt} = \frac{Z \cdot ec r}{C_0} \cdot V_{acc}(t)$$



$$V_{acc}(t) = r \cdot C_0 \cdot \frac{dB}{dt}$$

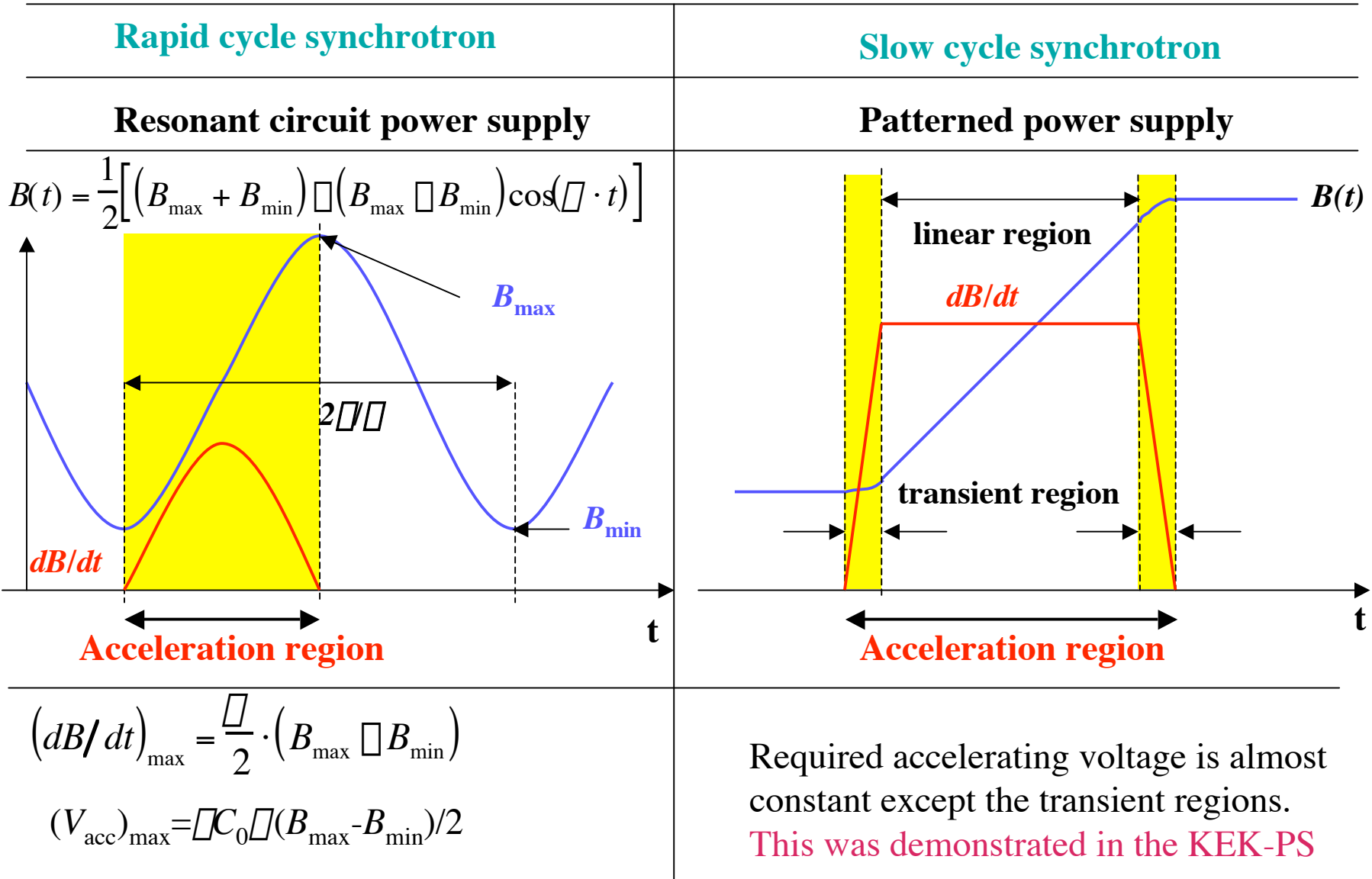


C_0 : circumference of the accelerator ring
 B : magnetic flux density of the bend. mag.
 r : bending radius
 (always fixed through the acceleration)

Required accelerating voltage V_{acc} is uniquely determined by dB/dt .

Acceleration in the AIA (2)

Change in an effective acceleration voltage by control of the gate-pulse density (Patent)



Revolution frequency and Switching frequency

revolution frequency:

$$f = c / C_0$$

$$f = \frac{c}{C_0} \sqrt{\frac{D}{1+D}}$$

$$D \equiv \left(\frac{Z}{A} \right)^2 = \left(\frac{Z}{A} \frac{e}{mc} \right)^2 B^2(t)$$

$$\frac{Z}{A} = \frac{Z}{A} \frac{e}{mc} B$$

kinetic energy as a function of the revolution frequency:

$$T = Mc^2 \left(\sqrt{1 + D} - 1 \right) = A \cdot mc^2 \left(\sqrt{1 + \left(\frac{Z}{A} \frac{e}{mc} B \right)^2} - 1 \right) = A \cdot mc^2 \left(\sqrt{1 + \left(\frac{Z}{A} \frac{e}{mc} \frac{c}{c} \frac{f \cdot C_0}{c} B \right)^2} - 1 \right)$$

Defect of the induction acceleration driven by the switching power supply:

Induction step voltage can't follow $V_{acc}(t)$.

It must be constant, V_0 , from a technical reason that it is difficult to change an output voltage of the DC power supply within tens of mseconds.

Counter measure: intermittent switching instantaneously averaged switching frequency $g(t)$

ΔE : energy gain per short time-period Δt

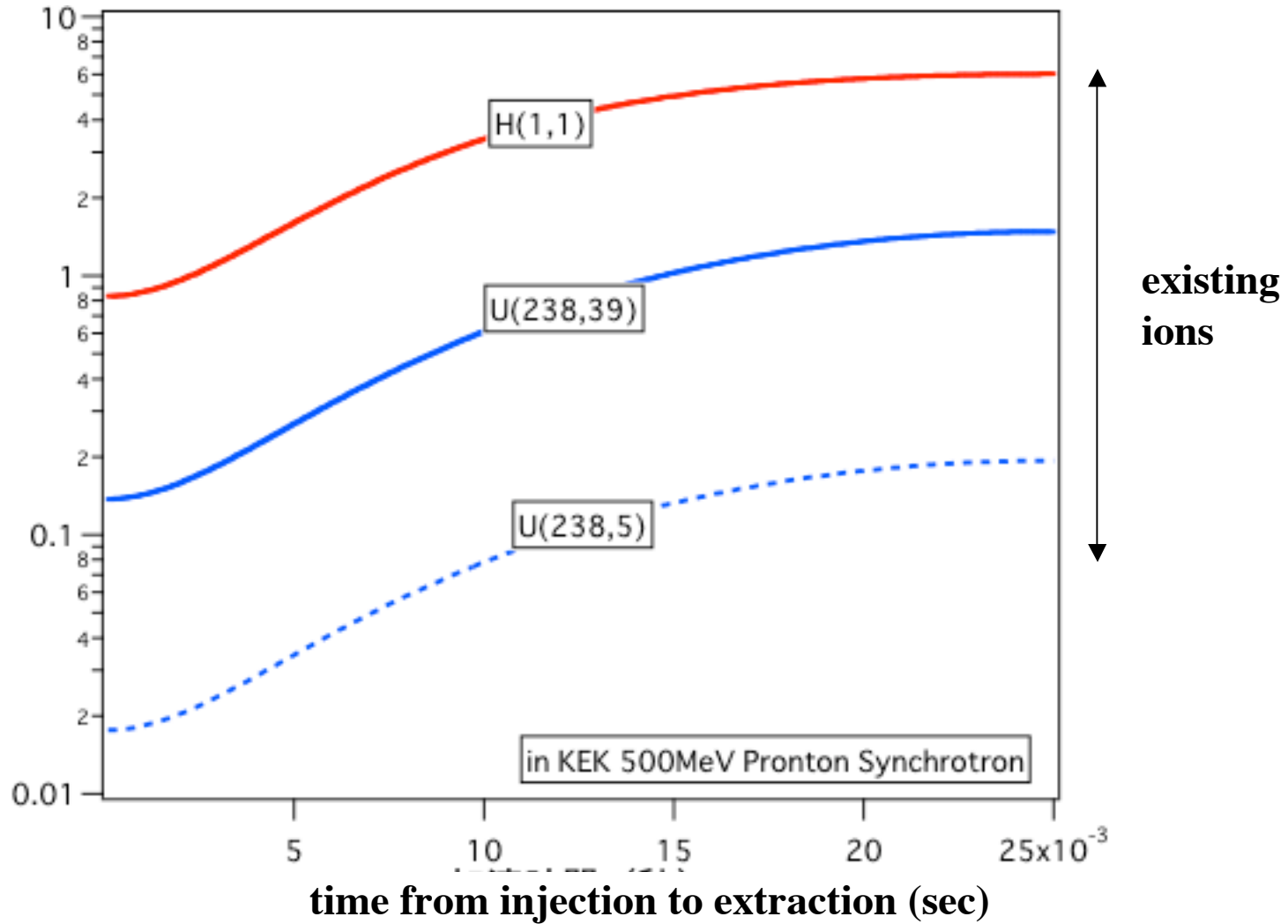
$$g(t) = (V_{acc}(t) / V_0) f(t)$$

$$\begin{aligned} \Delta E &= \int_t^{t+\Delta t} e V_{acc}(t) f(t) dt \\ &= e V_0 \int_t^{t+\Delta t} g(t) dt \end{aligned}$$

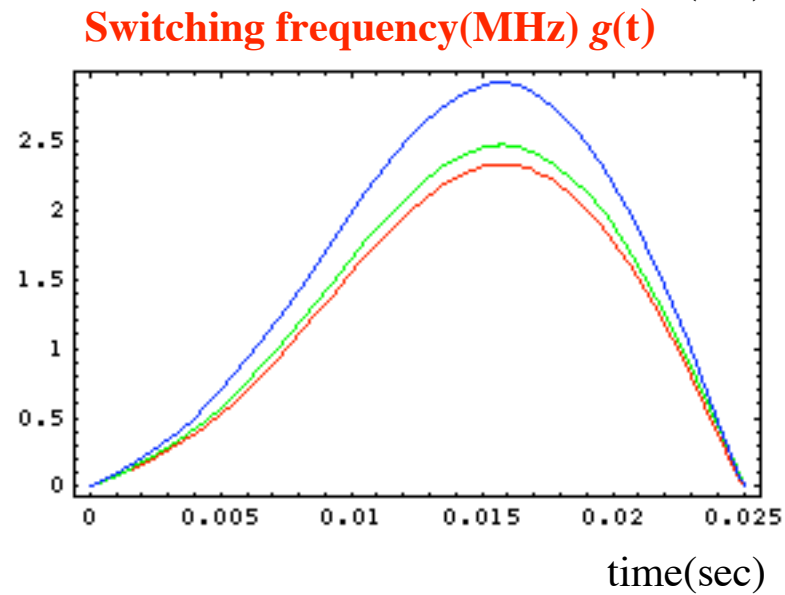
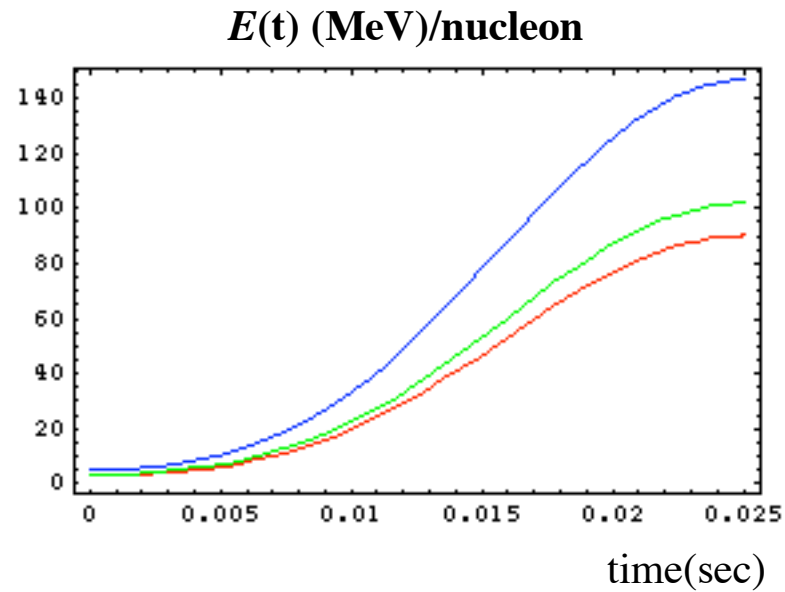
KEK 500MeV Booster & 12GeV PS

item	symbol	KEK 500MeV booster synchrotron		C: KEK 12GeV PS linear ramping
		A: excitation by resonant circuit	B: linear ramping	
circumference (m)	C_0	340/9	340/9	340
curvature (m)	\square	3.3	3.3	24.6
minimum field (T)	B_{min}	0.2	0.1	0.146
maximum field (T)	B_{max}	1.1	1.7	1.7
ramping time (sec)	\square	0.05	0.8	0.8
acceleration voltage (kV) from (3)	V_{acc}	7.05 (max)	0.25	16.3

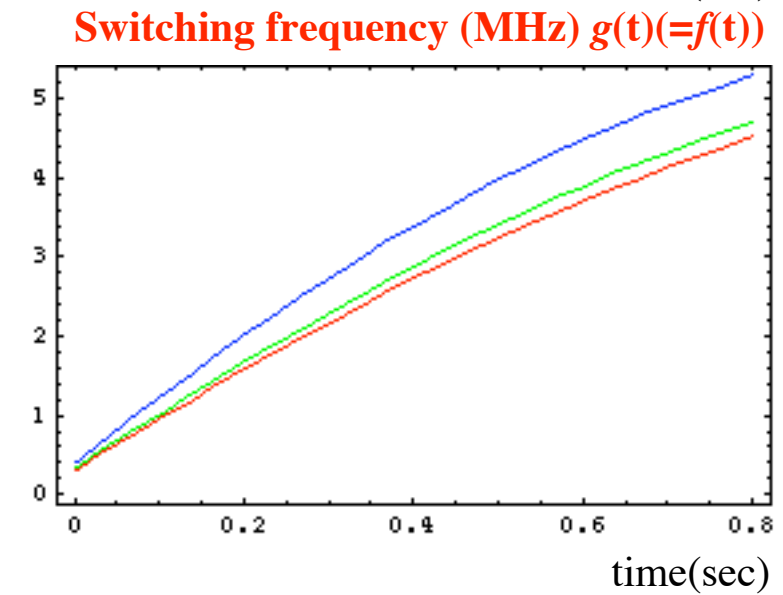
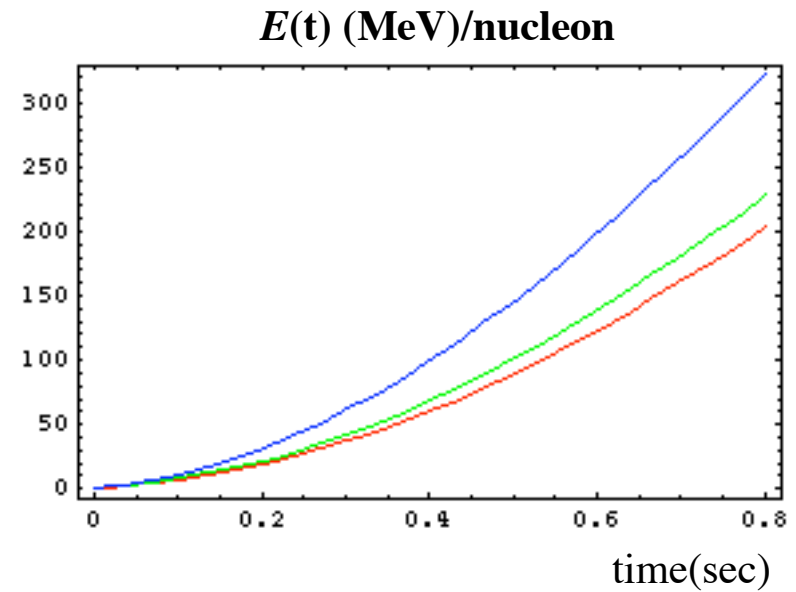
Revolution frequency (MHz)



Case A: sinusoidal ramp in Booster



Case B: linear ramp in Booster



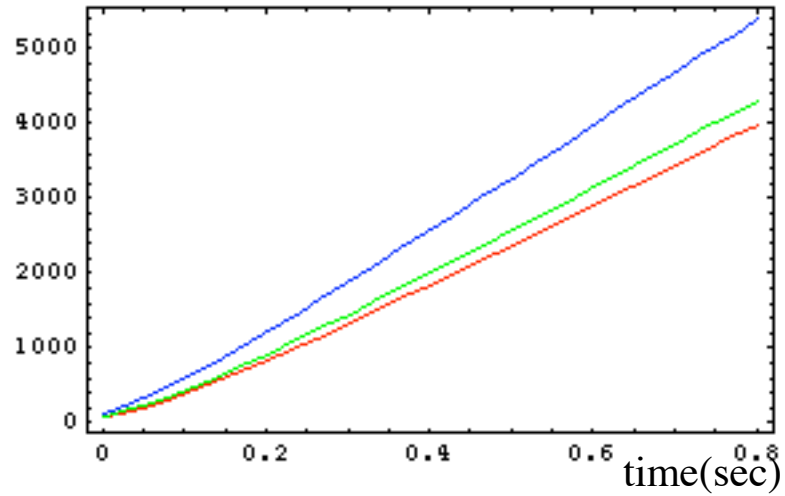
————— **O(16,8)**

————— **Xe(131,54)**

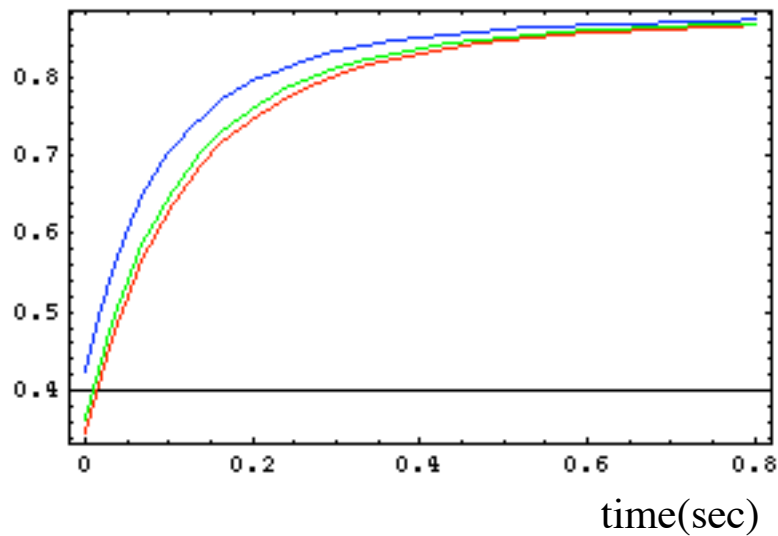
————— **U(238,92)**

Case C: linear ramp in 12GeV PS

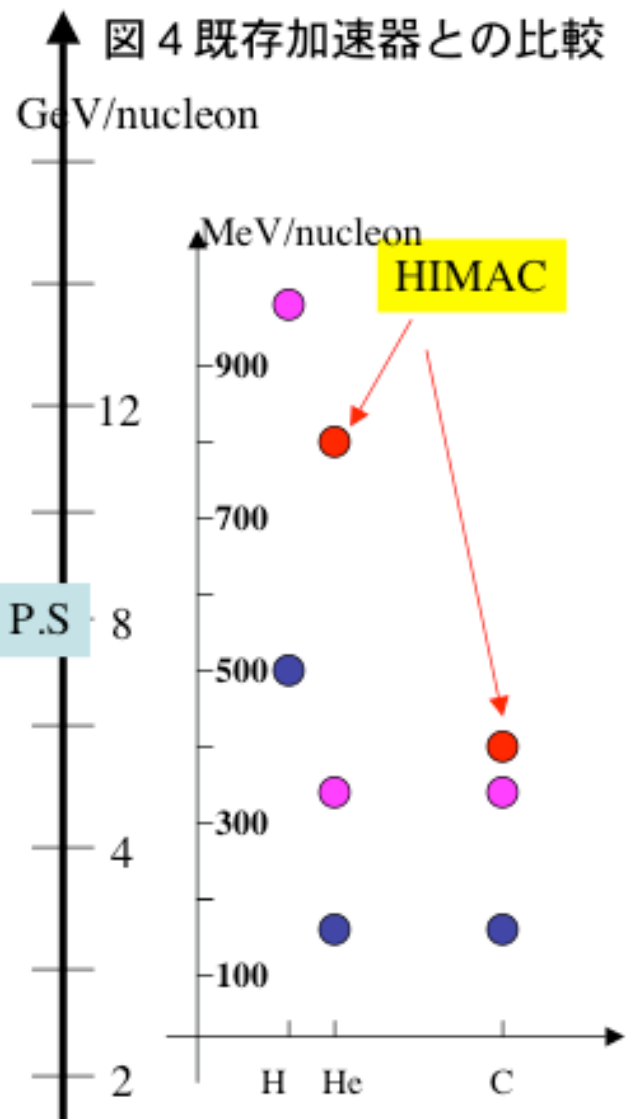
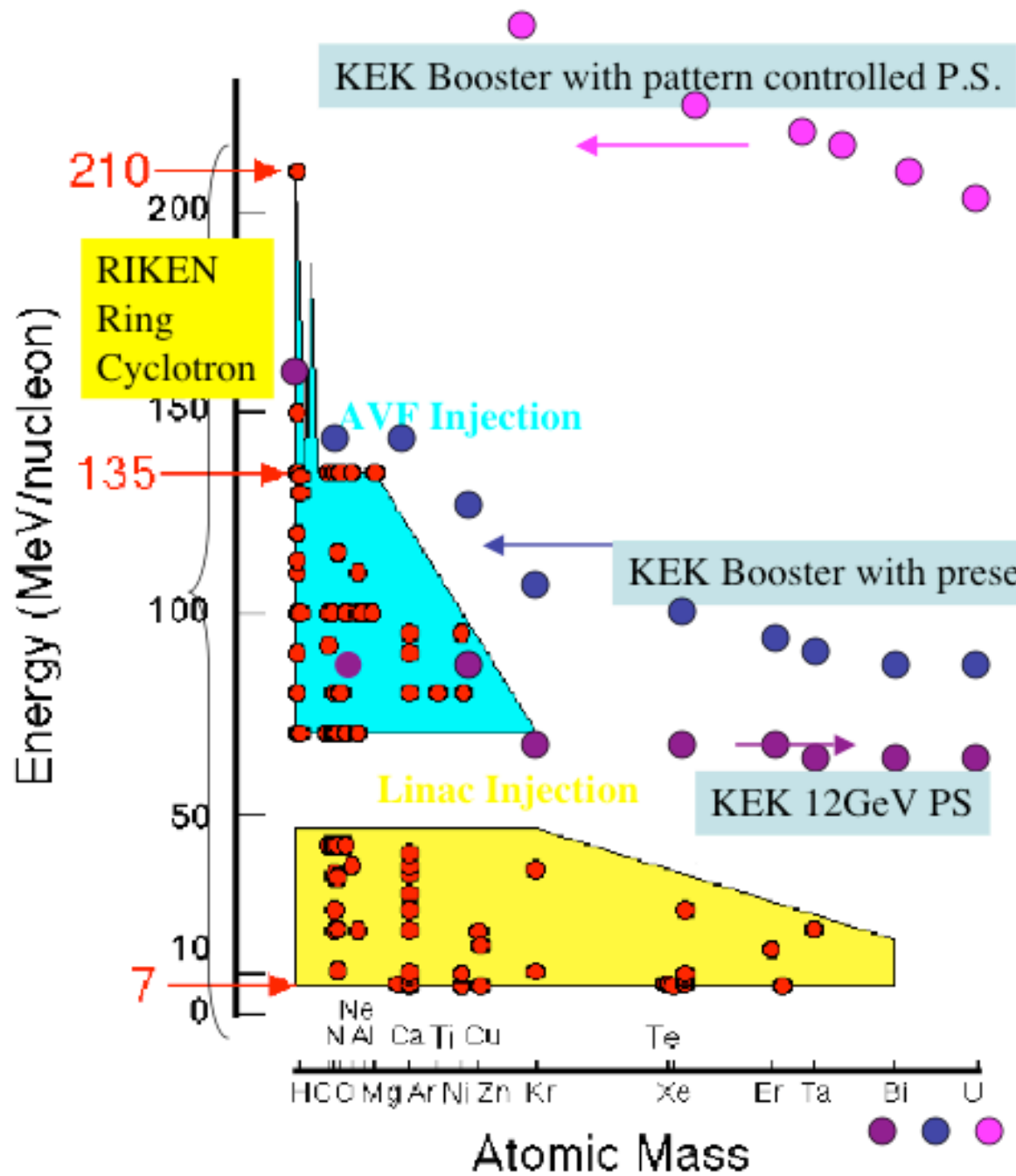
$E(t)$ (MeV)/nucleon



Switching frequency (MHz) $g(t)(=f(t))$



— O(16,8) — Xe(131,54) — U(238,92)



● ● ● : full ionization is assumed.

Transverse Focusing in the AIA

Equation of motion in the transverse direction: **Easy accelerator tuning for any ions**

$$A \cdot m \cdot \frac{d}{dt} (\beta \cdot v_{\perp}) = Z \cdot e \cdot v_{\parallel} \cdot B' x$$

with $B' \equiv \frac{\partial B_y}{\partial x}$

common
COD
Betatron tune
Injection/extraction orbit

gate timing is determined from the circulating bunch signal.

$$\beta \cdot c \cdot \frac{d}{ds} \left(\frac{dx}{ds} \right) = \frac{Z \cdot e}{A \cdot m} \cdot B' x \quad \frac{d^2 x}{ds^2} + K(s)x = 0$$

$$K(s) = \frac{Z}{A} \cdot \frac{(e/m)}{c} \cdot \frac{\partial B_y}{\partial x}$$

$$K(s) = \frac{\partial B_y / \partial x}{B}$$

Interesting option

Simultaneous acceleration of different ion species with different (Z/A) in the same ring

Betatron frequency doesn't depend on ion.

gate triggers are generated every ion species.

Current and future items for R&D on Induction accelerating system

item	necessity	measures
Droop compensation (2005)	<ul style="list-style-type: none"> •Droop gives additional focusing (above β) and defocusing (below β) •indispensable for acceleration of a super-bunch 	introduce an additional compensation cell
βR-feedback system (2005)	<ul style="list-style-type: none"> •The beam centroid must be hold on the design orbit. •There is no phase-feedback system as found in RF-synchrotrons. •to relax a precise control of the induction voltage 	apply for a patent (presented at PAC2005)
Low impedance system (2005-2006)	<ul style="list-style-type: none"> •have to stand up to significant beam loading caused by super-bunches •currently limited due to the arm current of the pulse modulator (deposited heat) 	<ul style="list-style-type: none"> •increase the arm current by a change in the circuit architecture •Otherwise employ other power switching elements •replace with transmission cable and matching resistance of low impedance

Summary

- A reliable full module for the induction accelerating system consisting of **50kW DC P.S., Pulse Modulator, Transmission Cable, Matching Resistance, Induction Cell**, which is capable of operating at 1 MHz, has been confirmed to run over 24 hours without any troubles.
- The *induction acceleration* of protons(6×10^{11} ppb) in a circular accelerator ring has been observed, where a single RF bunch was accelerated from 500MeV to 8GeV (flat-top) with an energy gain of 4.8 kV/turn.
- A *600nsec-long proton bunch* trapped in a shallow notch potential, which is generated with induction step-voltages, has been demonstrated.
- These results are crucial milestones to realize *Induction Synchrotrons* and *Super-bunch Hadron Colliders*.
- The acceleration in circular rings has entered into a new era with induction devices driven by a switching driver.

One of possible and unique applications in a low energy region may be All-ion Accelerator.

Appendix

Organizing Committee

K. Takayama (Chair, KEK)
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S. Holmes (FNAL)
I. Hofmann (GSI)

RPIA2006

2nd International Workshop on Recent Progress in Induction Accelerators

March 7-10, 2006
KEK, Tsukuba, Japan

Organized by
High Energy Accelerator Research Organization
Tokyo Institute of Technology

traditional trawling boats in Lake Kasumi (photo by K.Kuroda) *URL <http://conference.kek.jp/RPIA2006/>*

We will discuss

- **Induction devices for LINAC and Circular Ring
(Induction cell, Modulator, Switching elements, System architecture)**
 - **Hybrid system combining RF and Induction acceleration**
 - **Beam dynamics in extremely high intensity accelerators**
 - **Super-bunch beam dynamics, barrier-bucket beam dynamics**
 - **Applications**
 - Heavy Ion Fusion Driver**
 - Induction Synchrotron**
 - Super-bunch Hadron Collider, Super-bunch FFAG**
 - Novel Ion Accelerator**
 - Chopper, High-rep rate Kicker**
 - others**
- Contributions from Proton driver, Neutrino Factory, Hadron Collider,
Inertial Fusion, Pulsed-power technology, Linear Collider Societies
quite welcome**